

# Unnormalized Spectral Clustering

This form of relaxed RatioCut = **Unnormalized Spectral Clustering**

$$\arg \min_{F \in \mathbb{R}^{N \times k}} \text{Tr}(F^T \mathbf{L} F) \text{ such that } F^T F = \mathbb{I}$$

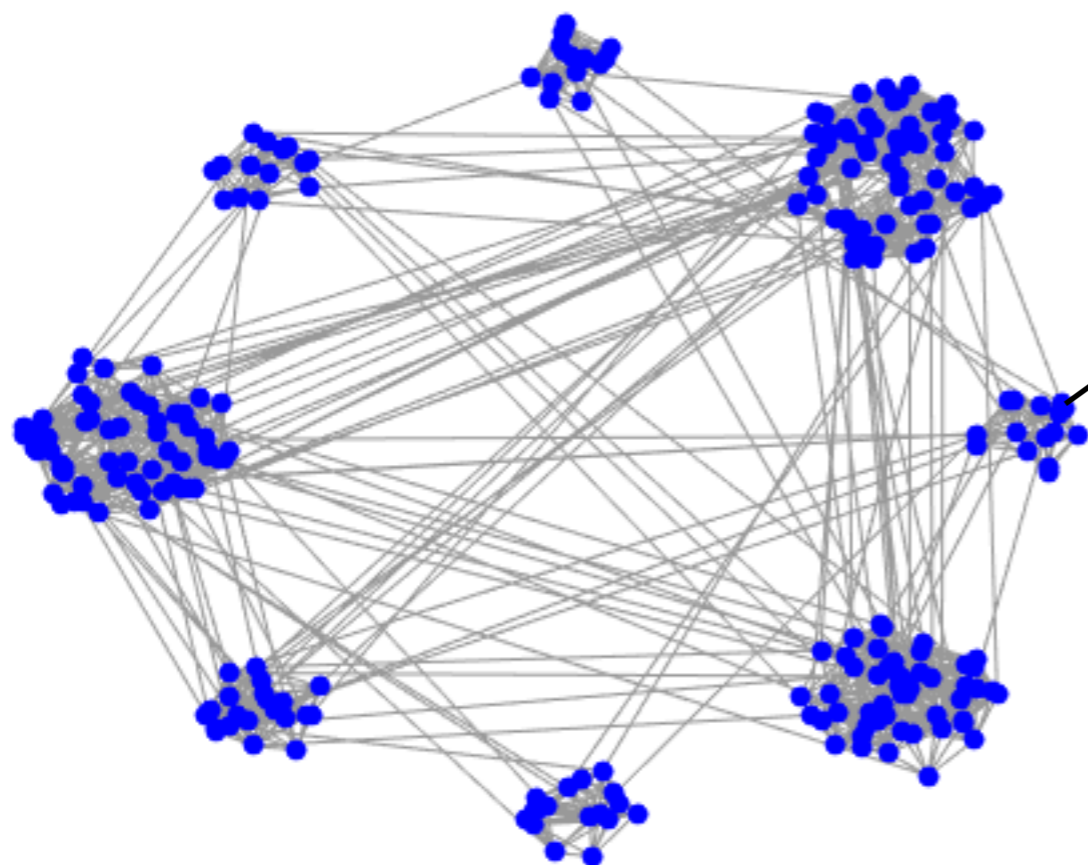
## Algorithm: Unnormalized Spectral Clustering

Compute the matrix  $F$  of first  $k$  eigenvectors of  $\mathbf{L}$

Apply k-means to rows of  $F$  to obtain cluster assignments

# What is the algorithm doing - view 1

At each vertex the algorithm associates a feature vector that represents the fine and large scale structure of that vertex's neighbourhood in the graph



vertex  $[i]$ , feature  $f_i \in \mathbb{R}^k$

$$f_i[\ell] = u_\ell[i], \quad \ell = 1, \dots, k$$

These are the lines of the matrix  $F$

If the graph has  $k$  disconnected components, what does  $F$  look like ?

$k$ -means is then applied to these vectors to cluster into  $k$  clusters

In short, the algorithm classifies vertices into  $k$  clusters blindly

# What is the algorithm doing - view 2

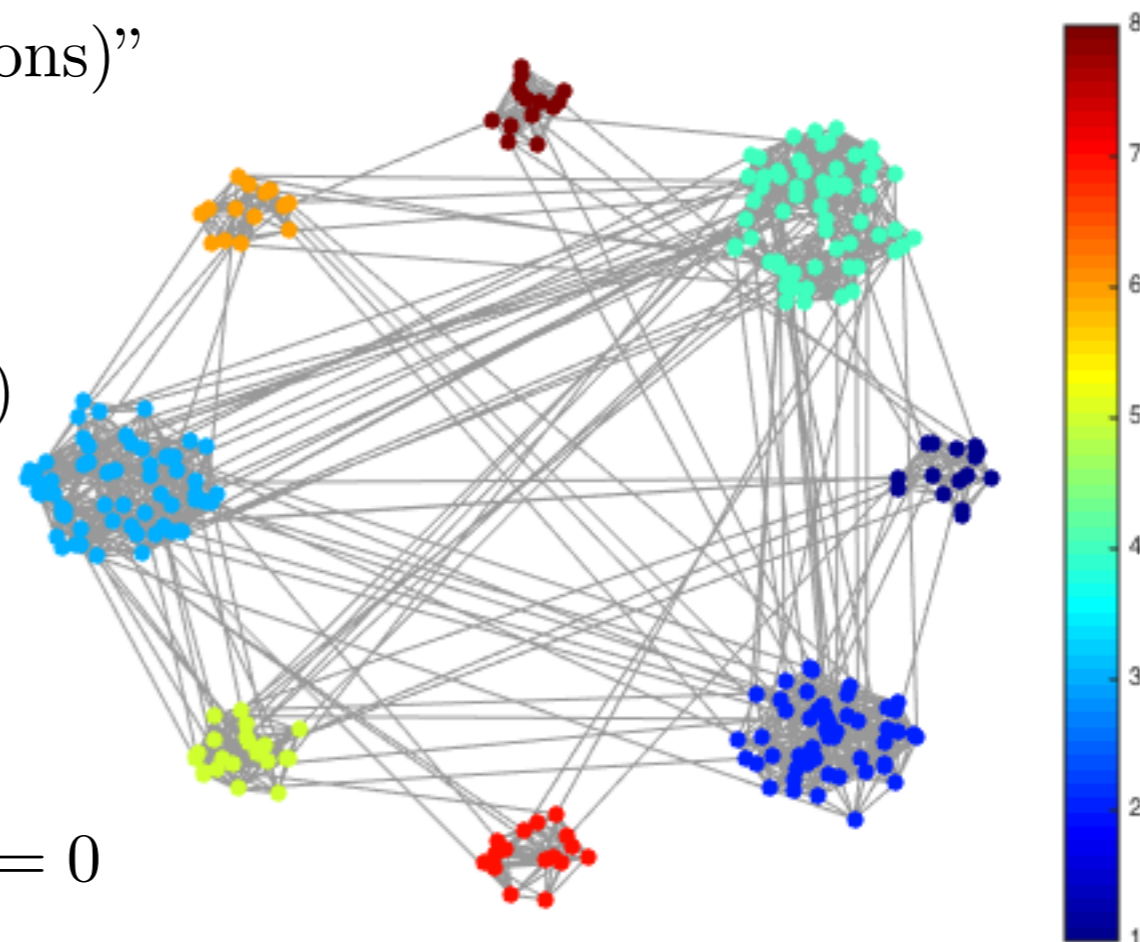
We are looking for  $k$  “partition signals (functions)”

$$f_\ell : V \mapsto \mathbb{R}$$

In the ideal case ( $k$  disconnected components)

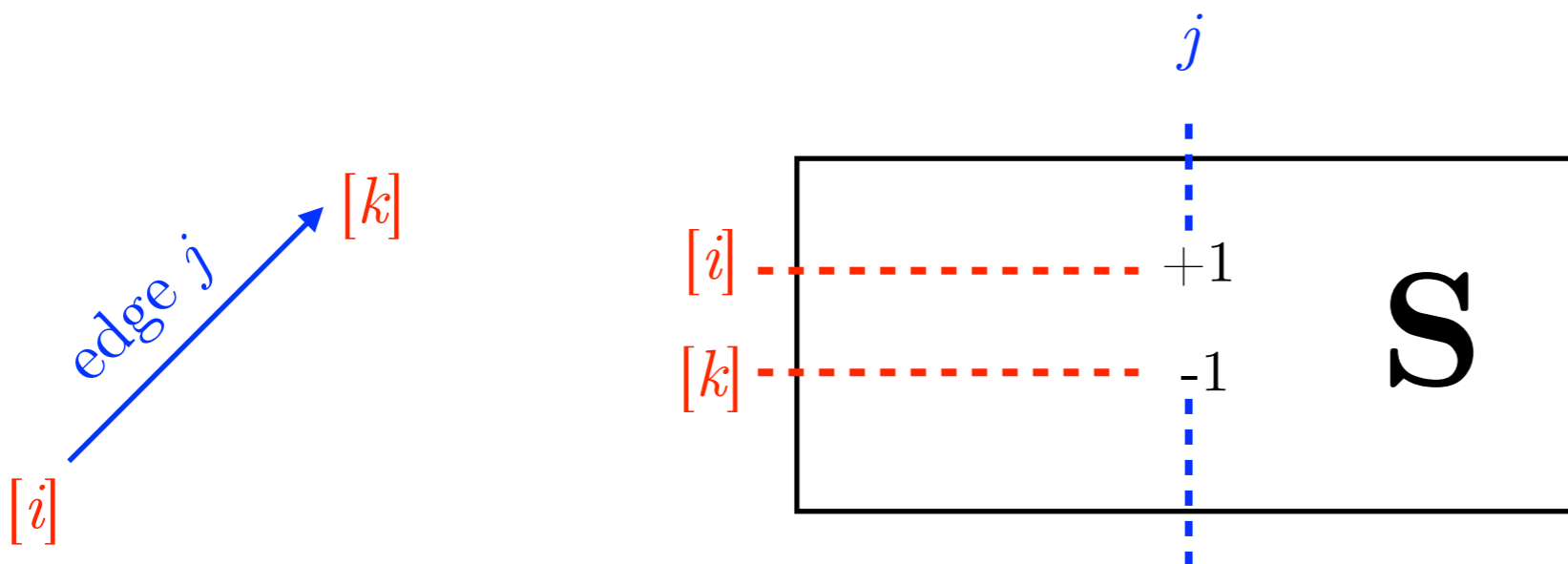
$$f_\ell[i] = \begin{cases} 1 & \text{if } i \in \text{cluster } \ell \\ 0 & \text{otherwise} \end{cases}$$

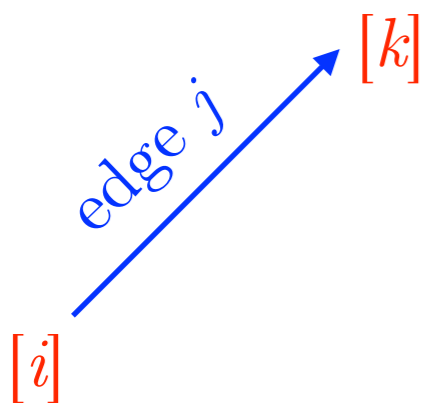
These are maximally **smooth** signals:  $f_\ell^T \mathbf{L} f_\ell = 0$



Incidence Matrix:  $\mathbf{S} \in \mathbb{R}^{N \times M}$   $N = |V|$ ,  $M = |E|$

$$\mathbf{S}(i, j) = \begin{cases} +1 & \text{if } e_j = (v_i, v_k) \text{ for some } k \\ -1 & \text{if } e_j = (v_k, v_i) \text{ for some } k \\ 0 & \text{otherwise} \end{cases}$$





Signal (function)  $f$  defined on the vertices  $f \in \mathbb{R}^N$

$(\mathbf{S}^T f)[j] = f[i] - f[k]$  derivative of  $f$  along edge  $j$

$\mathbf{S}^T f \in \mathbb{R}^M$  gradient of  $f$

$$\begin{aligned} \mathbf{L} = \mathbf{S}\mathbf{S}^T \quad f^T \mathbf{L} f &= f^T \mathbf{S}\mathbf{S}^T f \\ &= \|\mathbf{S}^T f\|_2^2 \\ &= \sum_{i \sim k} (f[i] - f[k])^2 \end{aligned}$$

In general for a weighted graph:  $f^T \mathbf{L} f = \sum_{i \sim k} \mathbf{W}(i, k) (f[i] - f[k])^2$

This quadratic (Dirichlet) form is a measure of how smooth the signal is

# Laplacian Eigenmaps

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# Spectral Graph Embedding

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Dataset is a large matrix  $X \in \mathbb{R}^{N \times L}$

$N$  is the number of data points

$L$  is the dimension of each data points

Often  $L \gg 1$  and must be reduced (think images)

For computations

For visualisation, in which case we would like  $L = 2, 3$

Q: can we reduce  $L$  in a way that resulting modified data stays faithful to the original one ?

# Formulation

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Find a mapping from the  $N$  high-dim data points to  $N$  low-dim points

$$x_1, \dots, x_N \mapsto y_1, \dots, y_N$$

$$x_i \in \mathbb{R}^L \quad y_i \in \mathbb{R}^P$$

Assumption: we have a graph of similarities among original data points

Similarities are often constructed by either :

selecting  $k$ -nearest neighbours of each point with distance  $d(x_i, x_j)$

OR

selecting all points in a neighbourhood  $d(x_i, x_j) \leq \epsilon$

THEN weighting these edges ex:  $\mathbf{W}(i, j) = e^{-d(x_i, x_j)^2/t}$



# Formulation

$\mathbf{W}$  captures similarities among data points  $x_i \in \mathbb{R}^L$

We want that similar points are **embedded close to each other**

Suppose we embed in 1 dimension ( $P=1$ )

$$\arg \min_{y_1, \dots, y_N} \sum_{i \sim j} \mathbf{W}(i, j) (y_i - y_j)^2 \quad \longrightarrow \quad \arg \min_{y \in \mathbb{R}^N} y^T \mathbf{L} y$$

Add a constraint to avoid collapse  $y=0$ :  $y^T \mathbf{D} y = 1$

Avoid trivial eigenvector:  $y^T \mathbf{D} \mathbf{1} = 0$

$$\longrightarrow \arg \min_{\substack{y \in \mathbb{R}^N \\ y^T \mathbf{D} y = 1 \\ y^T \mathbf{D} \mathbf{1} = 0}} y^T \mathbf{L} y$$

# Full problem

When we embed in  $P$  dimension ( $P > 1$ )

$$\arg \min_{y_1, \dots, y_N} \sum_{i \sim j} \mathbf{W}(i, j) \|y_i - y_j\|_2^2$$

## Algorithm: Laplacian Eigenmaps

Collect the coordinates of embedded points as lines of matrix  $Y$

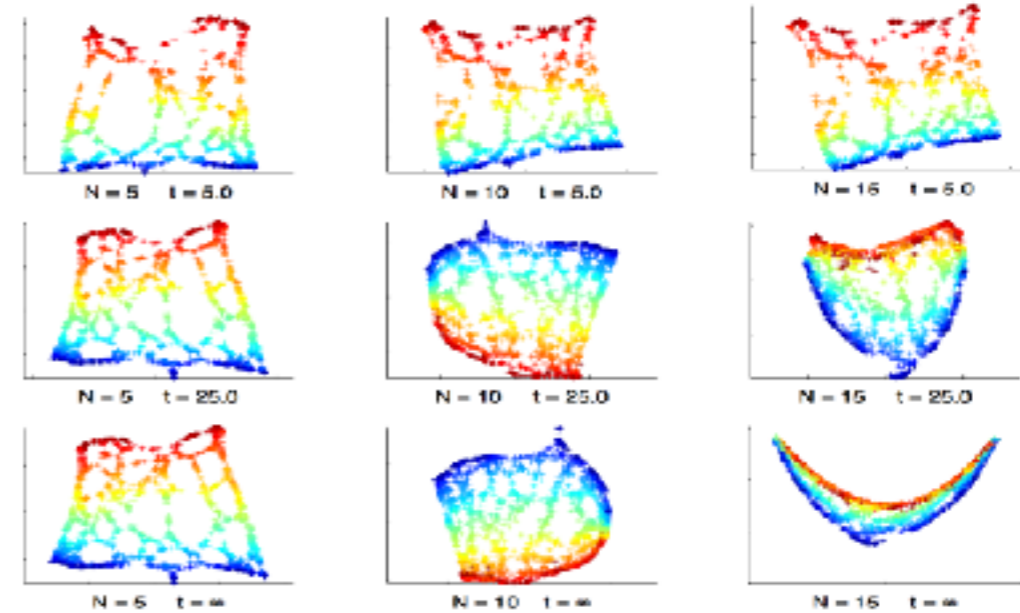
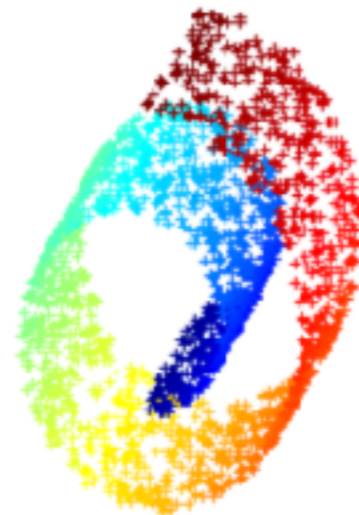
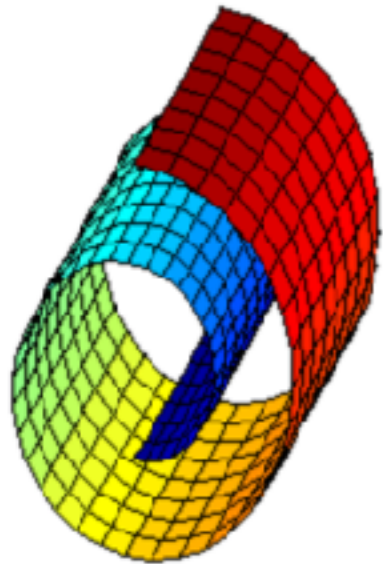
$$\arg \min_{Y \in \mathbb{R}^{N \times P}} \text{tr}(Y^T \mathbf{L} Y)$$

$$Y^T \mathbf{D} Y = \mathbb{I}$$

Laplacian Eigenmaps produces coordinate maps that are smooth functions over the original graph. Note similarity with clustering !

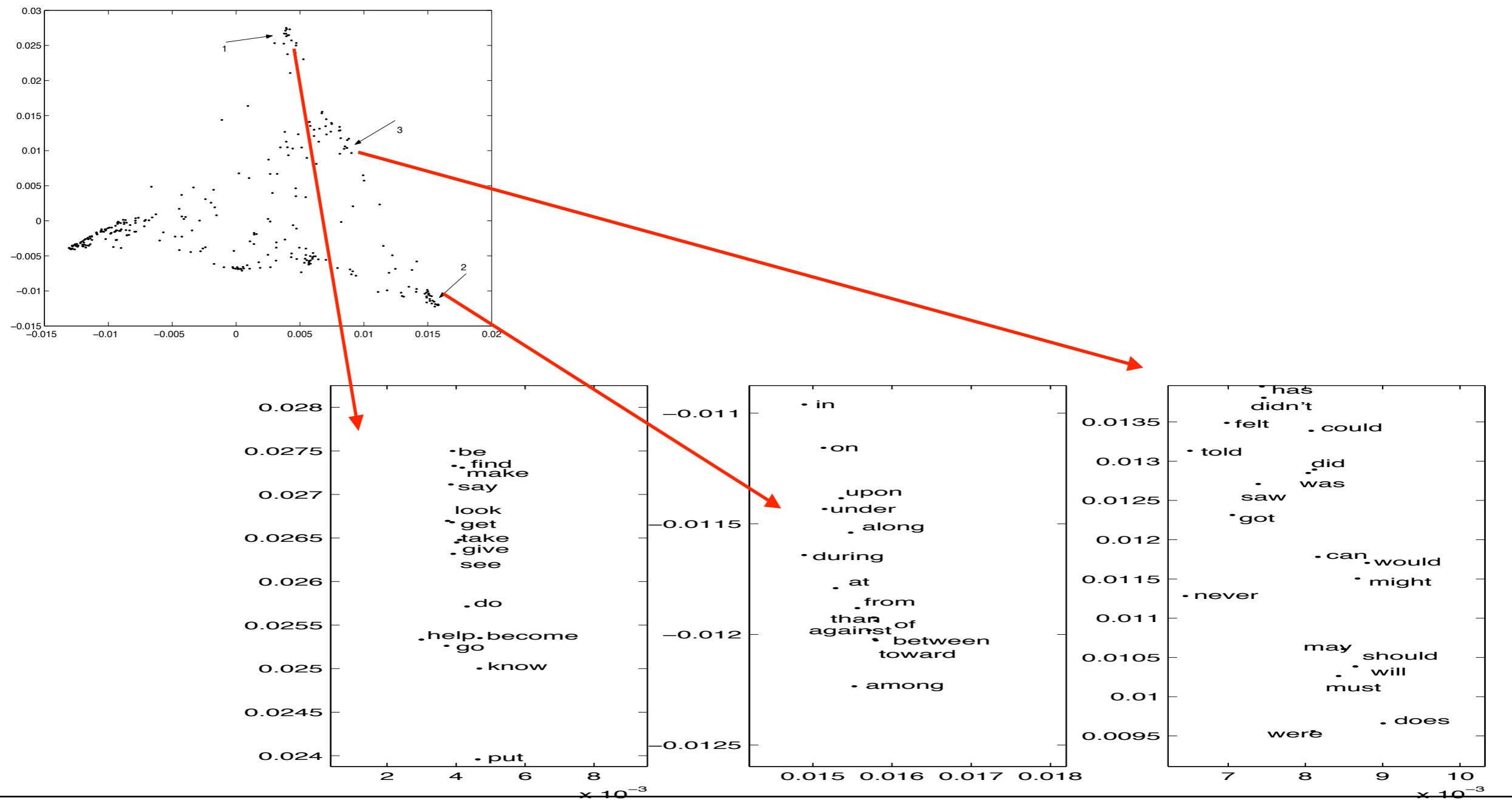
# Examples: synthetic

M. Belkin and P. Niyogi, "Laplacian eigenmaps for dimensionality reduction and data representation," *Neural Comput*, vol. 15, no. 6, pp. 1373–1396, 2003.



# Examples: text

M. Belkin and P. Niyogi, "Laplacian eigenmaps for dimensionality reduction and data representation," *Neural Comput*, vol. 15, no. 6, pp. 1373–1396, 2003.



# Examples: speech

